

## Students:

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# Smart Helmet: Connecting Cyclists to Intelligent Vehicles

## ENSC 02 Self-Proposed Project



School of Engineering  
& Applied Science

### Problem

#### Cyclist Safety in the Presence of Smart and Autonomous Vehicles

### Solution

A Battery-Powered Helmet, with GPS and wireless Vehicle-to-Everything (V2X) communication, that warns the cyclist of potential collisions via haptic and audible alerts.

### Design

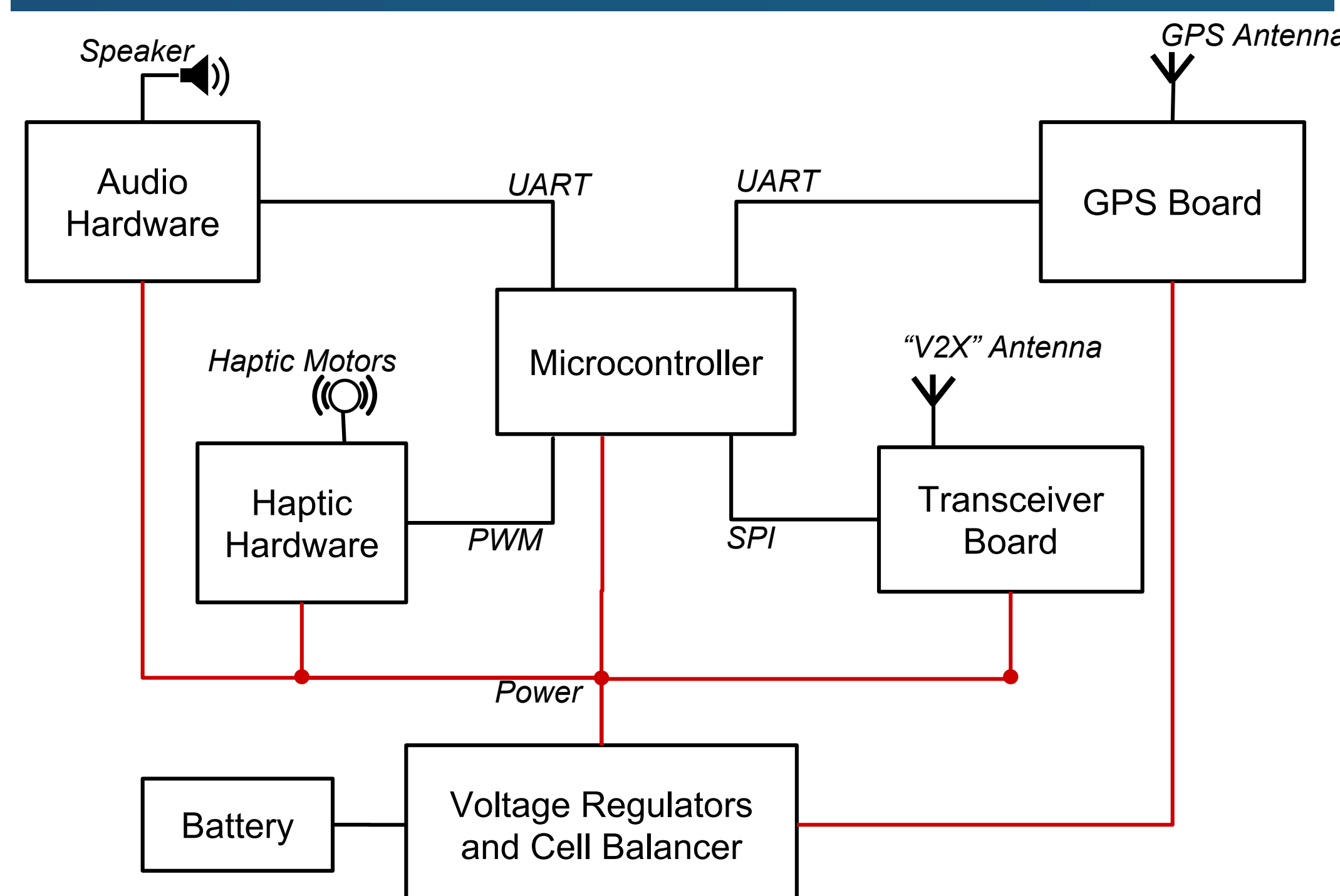


Figure 1: Block Diagram of Full Design

#### Requirements:

- GPS ✓
- V2X ✓
- Risk Assessment ✓
- Battery Power ✓
- Audio Warnings ✓
- Traffic Simulator ✓

#### Stretch Goals:

- Haptic Warnings ✓
- Custom PCB ~
- Bluetooth App ✗
- Module Enclosure ✗
- Signal Lights ✗



Figure 2: V2X on the Road

### What is V2X?

#### Vehicle-To-Everything Communication

- 5G Wireless
- Basic Safety Messages (Cars)
- Personal Safety Messages (People)
- Shared Data: position, size, motion, route data

### Printed Circuit Board (PCB) Design

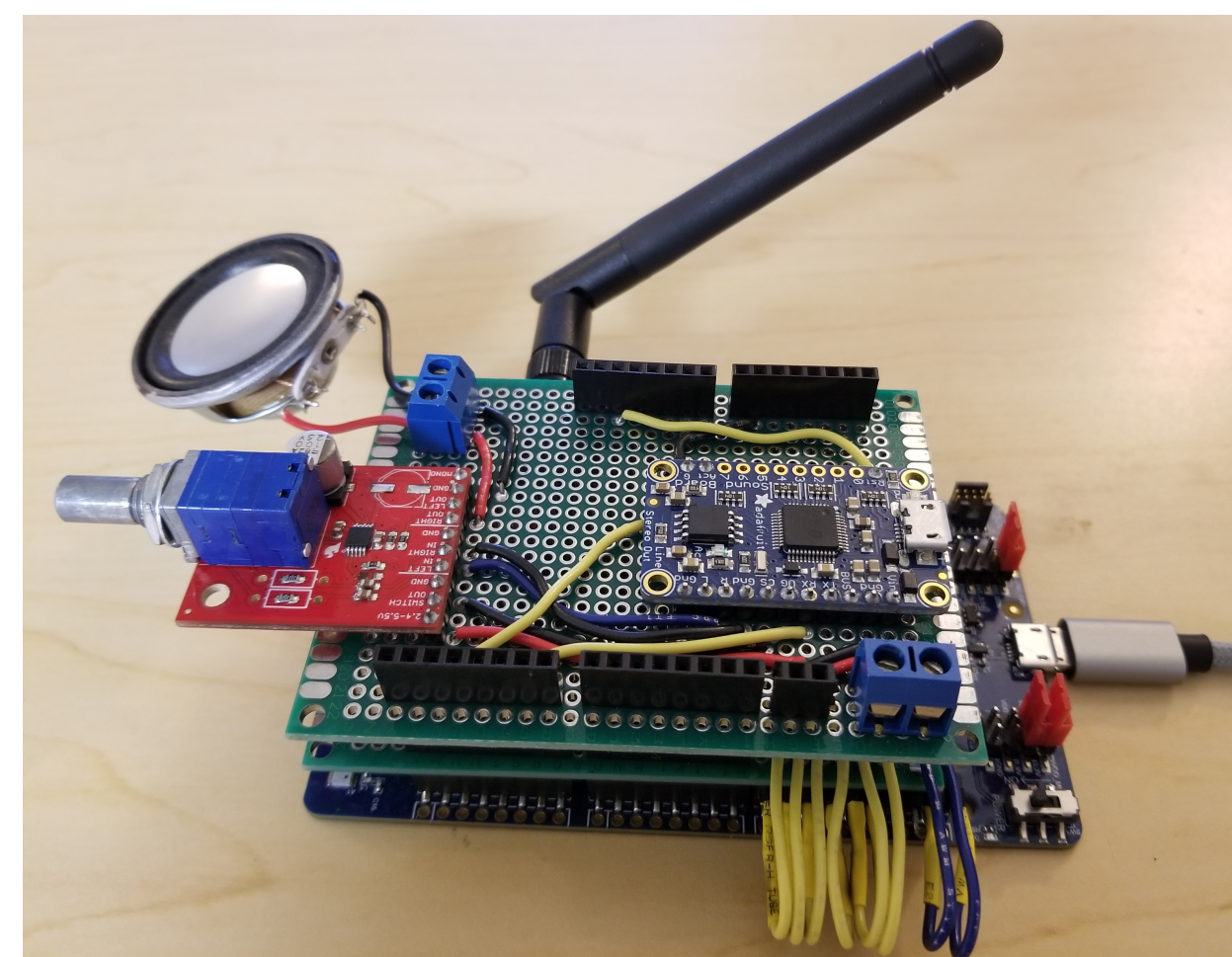


Figure 2: The Prototype Smart Helmet

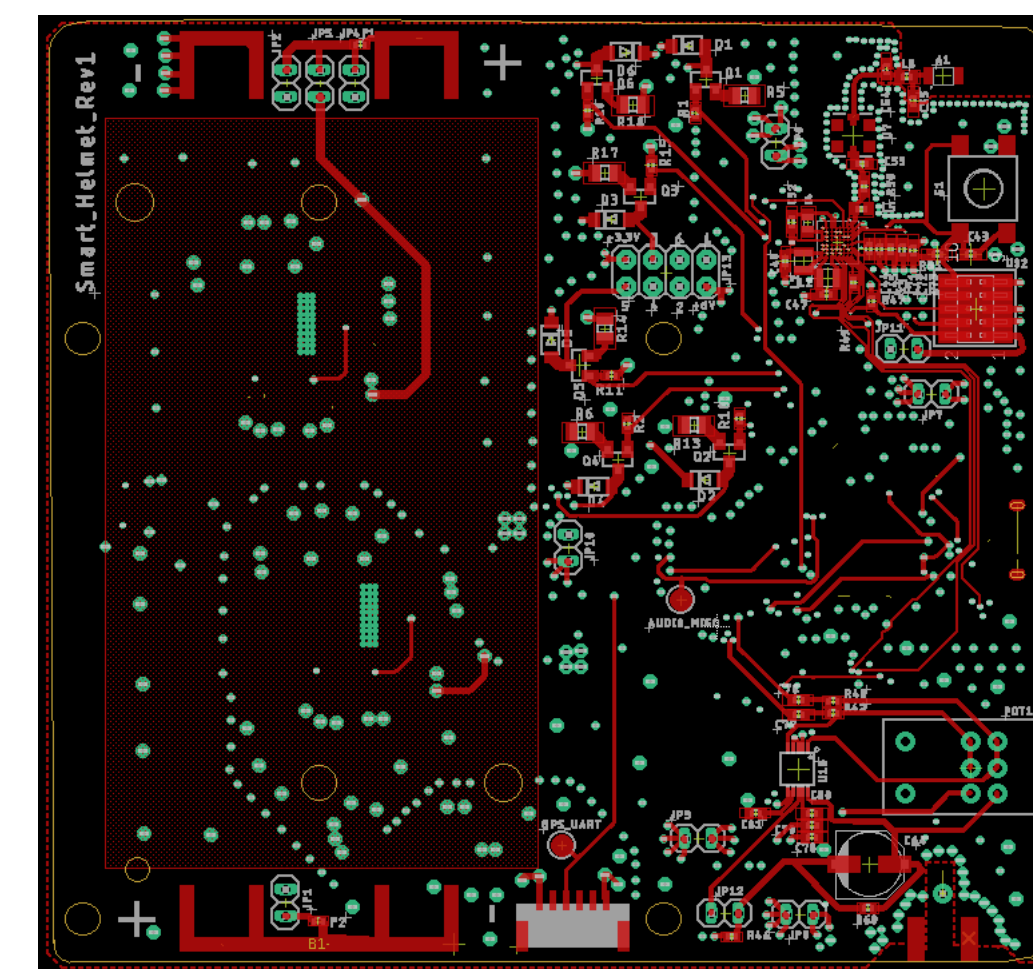


Figure 3: Full PCB Top Layer

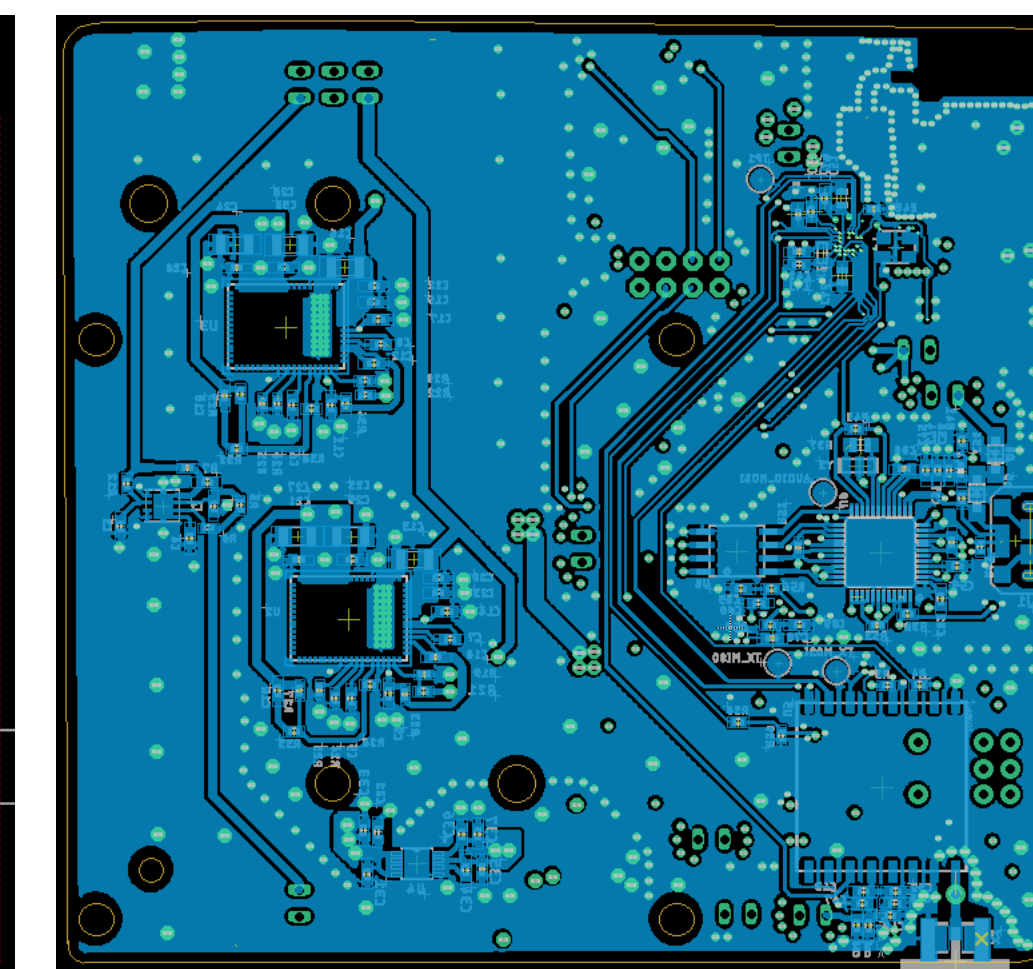


Figure 4: Full PCB Bottom Layer

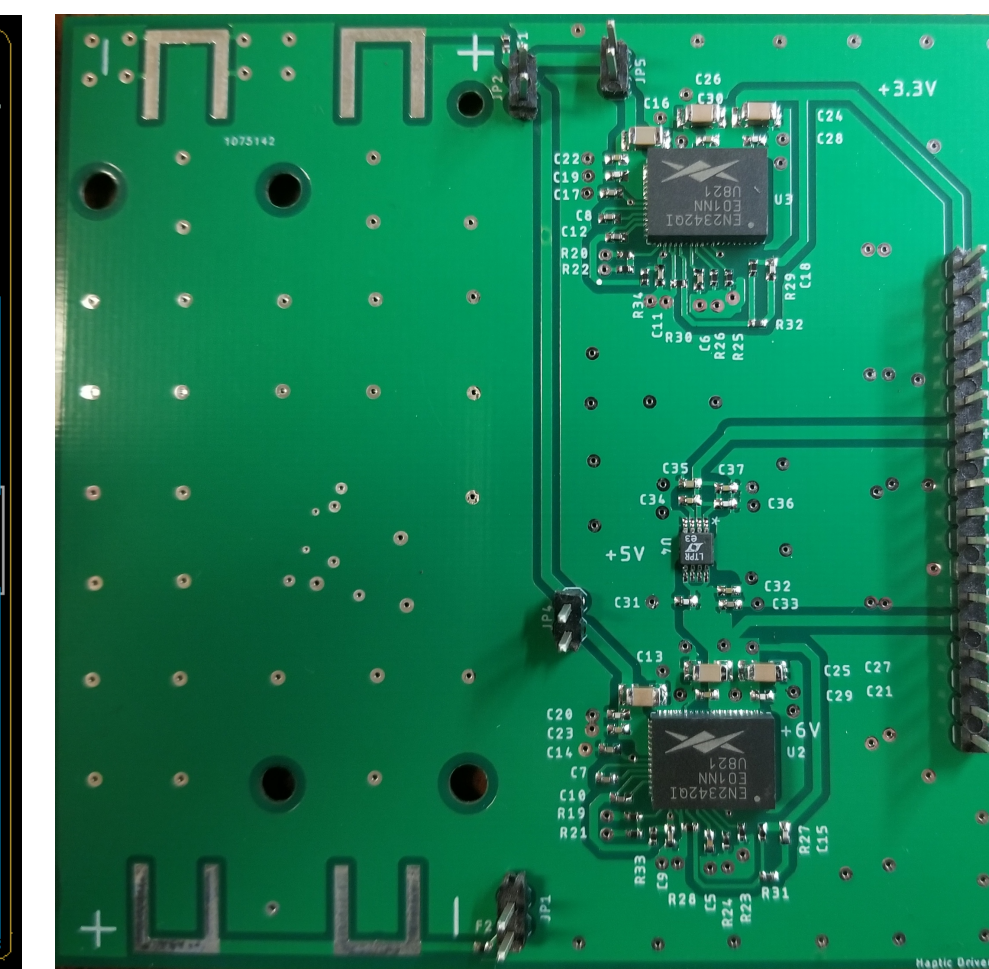


Figure 5: 2<sup>nd</sup> PCB Revision with Power and Haptics

#### Full System PCB:

- 4 Layers
- 198 components
- 3<sup>rd</sup> Iteration

#### Functionality:

- Power Supply
- Microcontroller
- Haptic Control
- Audio Processing
- V2X Messages
- Bluetooth

### Core Software

The core software running on the Smart Helmet's ultra low power **Apollo2 Blue** microcontroller uses the **Free RTOS** Real Time Operating System to handle task scheduling in the embedded and single-threaded environment of the helmet.

#### Free RTOS Tasks:

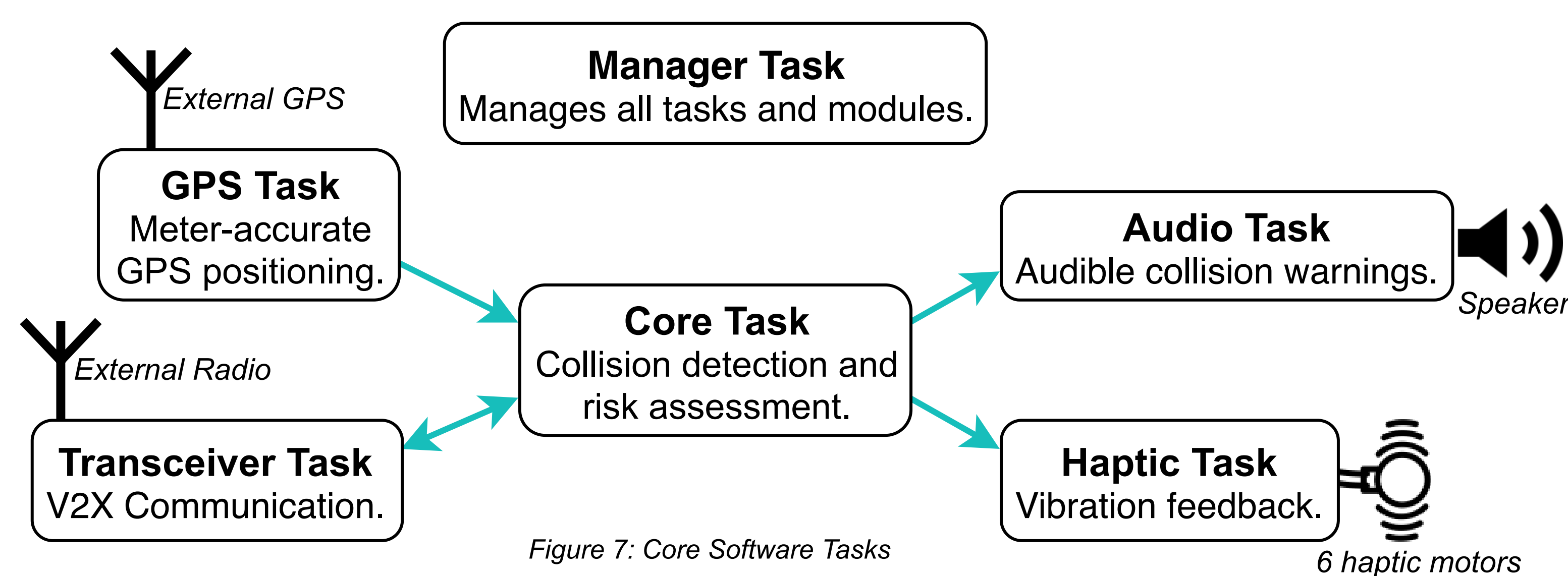


Figure 7: Core Software Tasks

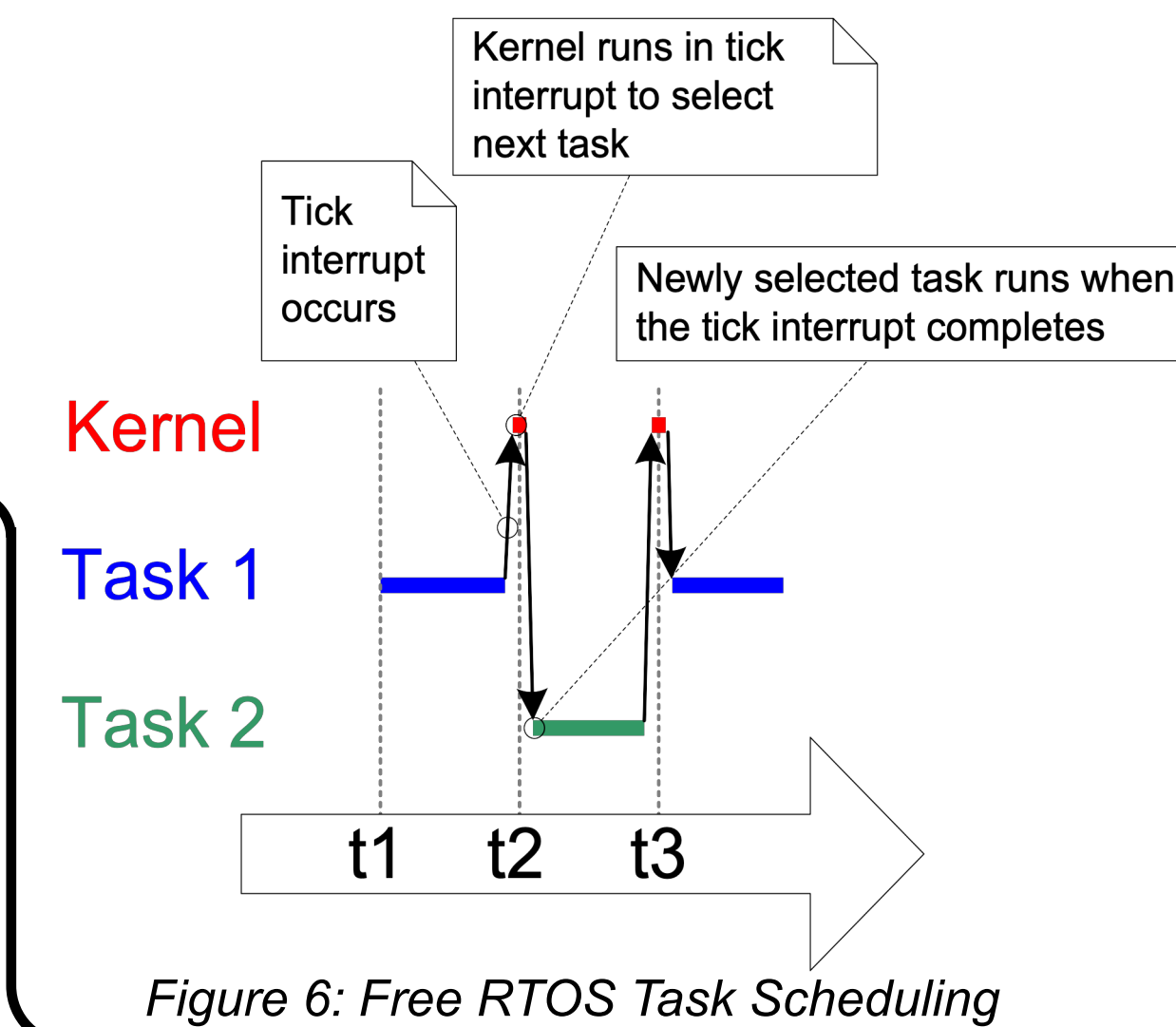


Figure 6: Free RTOS Task Scheduling

**Testing:** (with the Ceeding Framework)

- Unit Tests for collision detection algorithms.
- System Tests for custom PCB hardware.

### Traffic Simulator

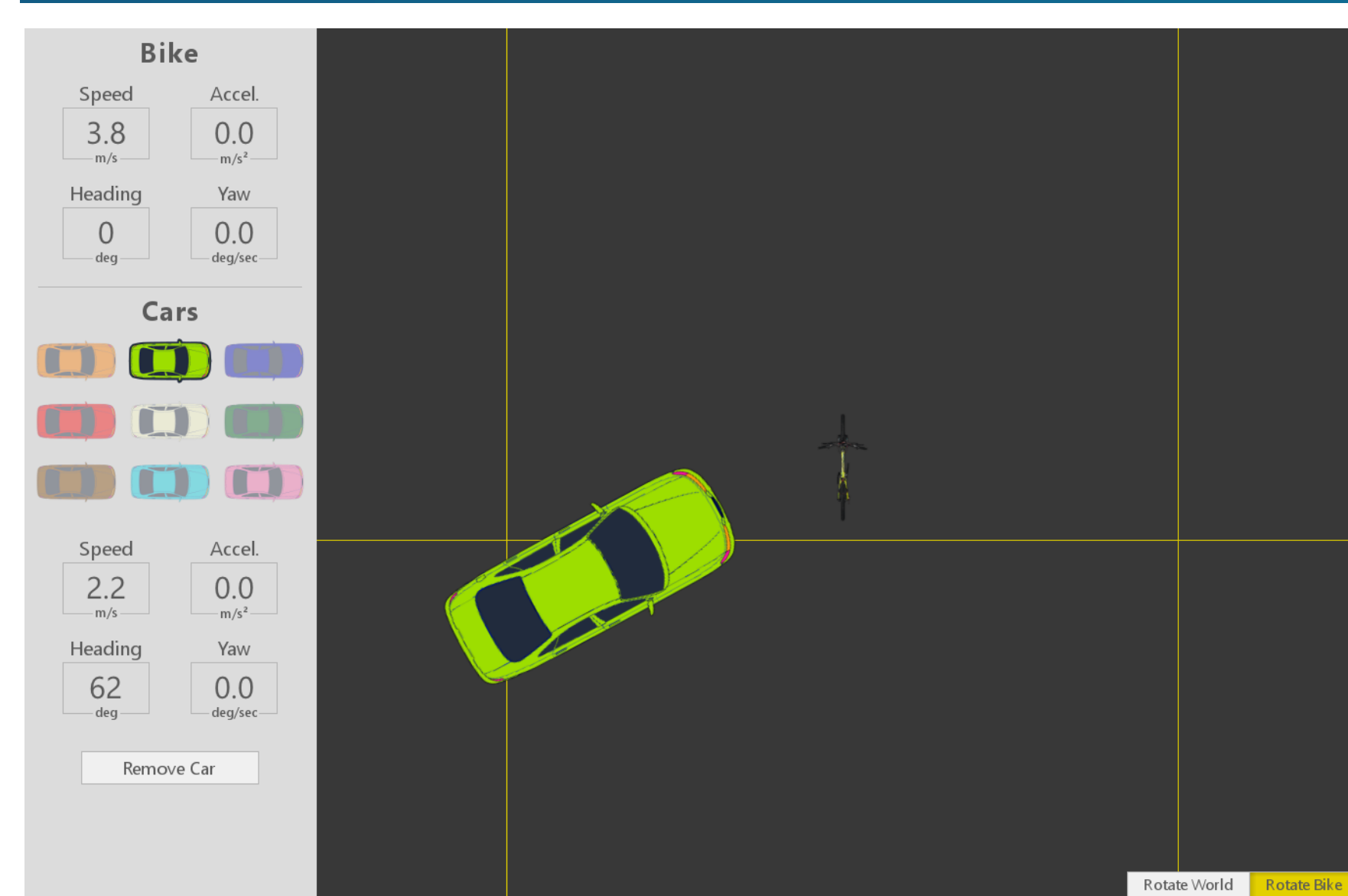


Figure 8: The Traffic Simulator

#### Java Desktop Traffic Simulator using OpenGL Graphics

Connects via USB to transceiver relay to spoof vehicle data to the Smart Helmet. Allows the user to generate cars in collision scenarios around the cyclist. The bike and currently selected car can be driven using the keyboard, and the motion data for the two are shown as well.

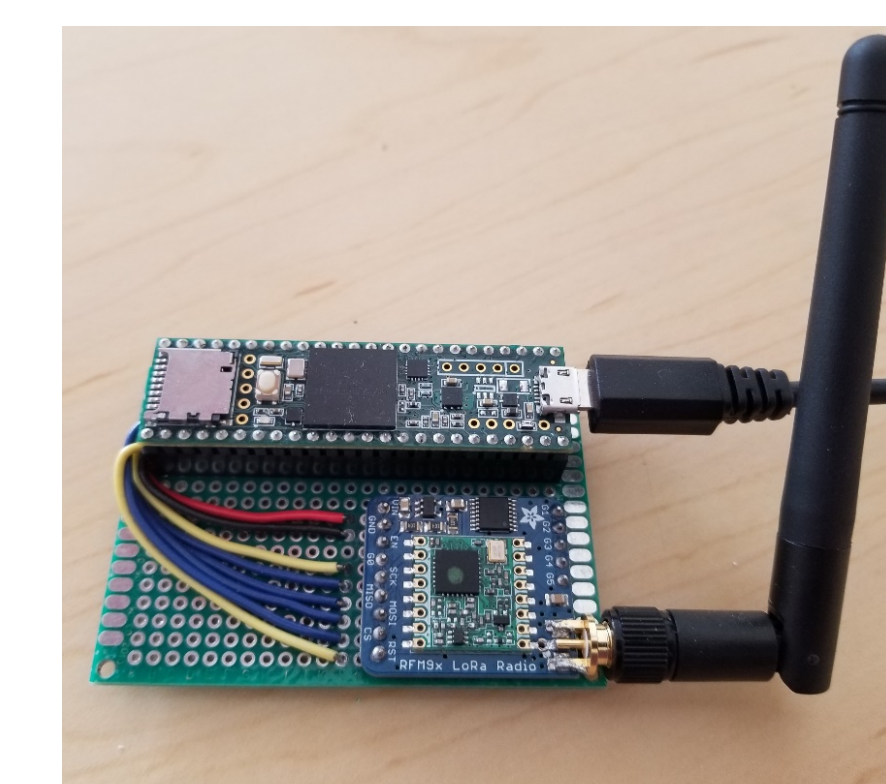


Figure 9: The Traffic Simulator's Transceiver Relay

### Results

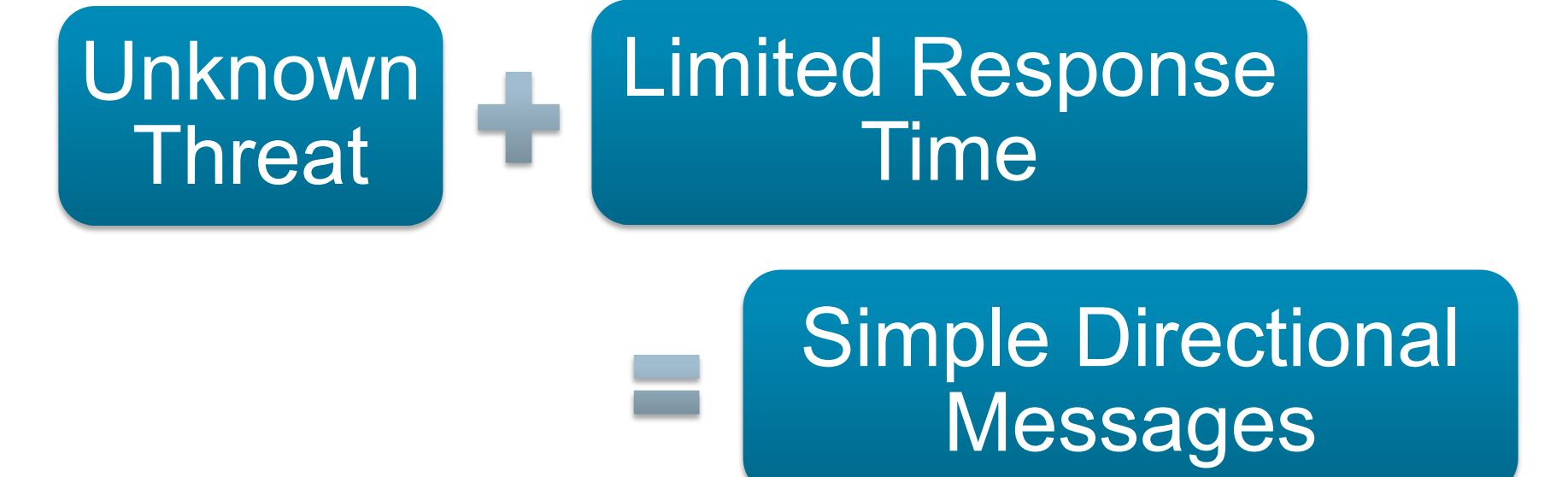
#### New Product Material Cost:

Quantity	Cost
1	\$292.00
100	\$165.00
1000	\$122.00

#### Collision Detection:

- |                            |                                   |
|----------------------------|-----------------------------------|
| <u>Limitations:</u>        | <u>Capabilities:</u>              |
| • Lack of Processing Power | • Linear and Curving Trajectories |
| • No Map Data              | • 10 second lookahead             |

#### Audio Warnings:



#### Haptic Warnings:

- 6 directional vibration motors.
- Buzzing frequency increases as threat approaches.
- Alternates among top 3 threats.

#### Project Budget:

Budget	Spent
\$5,000.00	\$2,600.00

### Next Steps

1. Authentic V2X radios.
2. Full printed circuit board with custom helmet.
3. Advanced inertial and proximity sensors for versatile collision warnings.
4. Bluetooth app for personalization and visual threat feedback.

Qualcomm  
9150 C-V2X

